

GENERAL LINEAR MODEL

- y_t : DEPENDENT VAR (REGRESSAND)
- $X_{t1}, X_{t2}, X_{t3}, \dots, X_{tK}$ EXPLANATORY VARIABLES (REGRESSORS), K variables
- $\beta_1, \beta_2, \beta_3, \dots, \beta_K$ coefficients
- X_{t1} USUALLY IS A VECTOR OF ONES, HENCE β_1 IS INTERCEPT, while $\beta_2 \dots \beta_K$ ARE SLOPE COEFFICIENTS : $\beta_K = \frac{\partial y_t}{\partial X_{tK}}$

MODEL:

- $$Y_t = \beta_1 X_{t1} + \beta_2 X_{t2} + \dots + \beta_K X_{tK} + \epsilon_t$$

ASSUMPTIONS:

1. vector of obs on y can be expressed as a linear combination of the sample obs on the

explanatory X plus a disturbance term.

for every obs t we have

$$Y_1 = \beta_1 + \beta_2 X_{12} + \beta_3 X_{13} + \dots + \beta_K X_{1K} + e_1$$

$$Y_2 = \beta_1 + \beta_2 X_{22} + \beta_3 X_{23} + \dots + \beta_K X_{2K} + e_2$$

$$Y_3 = \beta_1 + \beta_2 X_{32} + \beta_3 X_{33} + \dots + \beta_K X_{3K} + e_3$$

$$\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots$$

$$Y_T = \beta_1 + \beta_2 X_{T2} + \beta_3 X_{T3} + \dots + \beta_K X_{TK} + e_T$$

$$\begin{bmatrix} Y_1 \\ Y_2 \\ Y_3 \\ \vdots \\ Y_T \end{bmatrix} = \begin{bmatrix} 1 & X_{12} & X_{13} & \dots \\ 1 & X_{22} & X_{23} & \dots \\ 1 & X_{32} & X_{33} & \dots \\ \vdots & \vdots & \vdots & \vdots \\ 1 & X_{T2} & X_{T3} & \dots \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \vdots \\ \beta_K \end{bmatrix} + \begin{bmatrix} e_1 \\ e_2 \\ e_3 \\ \vdots \\ e_T \end{bmatrix}$$

$$Y = \underset{T \times 1}{\begin{matrix} X \\ \diagdown \\ T \times K \end{matrix}} \underset{K \times 1}{\beta} + \underset{T \times 1}{e}$$

Within $X = [x_1 \ x_2 \ x_3 \dots x_K]$ where $\underset{1 \times 3}{X} = \begin{bmatrix} 1 & 1 & 1 \\ x_1 & x_2 & x_3 \\ \vdots & \vdots & \vdots \end{bmatrix}$

$$x_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ \vdots \\ i \end{bmatrix}, \quad x_2 = \begin{bmatrix} x_{12} \\ x_{22} \\ x_{32} \\ \vdots \\ x_{T2} \end{bmatrix}, \quad x_3 = \begin{bmatrix} x_{13} \\ x_{23} \\ x_{33} \\ \vdots \\ x_{T3} \end{bmatrix}, \quad \text{etc.}$$

2. $E_x(e) = 0$, i.e. $E_x(y) = x\beta$

3. $E_x(ee') = \sigma^2 I_T$ **VARIANCE MATRIX**

$$e_x \sim (0, \sigma^2 I_T)$$

and

$$E_x[(y - x\beta)(y - x\beta)'] = E_x[ee'] = \sigma^2 I_T$$

$$y|x \sim (x\beta, \sigma^2 I_T)$$

$$\text{var}_x(e) = E_x(ee') = \begin{bmatrix} \underline{\text{var } e_1} & \text{cov}(e_1, e_2) & \dots & \text{cov}(e_1, e_k) \\ \text{cov}(e_2, e_1) & \underline{\text{var } e_2} & & \\ \vdots & & \ddots & \\ \text{cov}(e_T, e_1) & & & \underline{\text{var } e_T} \end{bmatrix}$$

- each e has the same variance σ^2 and mean 0.
- all disturbances are pairwise uncorrelated.

4. $p(X) = K$

The explanatory variables (including $x_1 = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$) do not form a linearly dependent set.

for example, if we had just two explanatory variables x_2 and x_3 and this assumption was not fulfilled, there would exist an exact relationship

$$x_3 = c_1 + c_2 x_2$$

$$x_3 = 1 + 2x_2$$

which \Rightarrow

$$Y = \beta_1 + \beta_2 x_2 + \beta_3 x_3 + e$$

$$Y = (\beta_1 + \beta_3 c_1) + (\beta_2 + \beta_3 c_2) x_2 + e$$

*

the constants c_1 and c_2 can be determined exactly and we can estimate the intercept and slope of * but there is NO WAY to obtain estimates of β parameters

5. X is a NONSTOCHASTIC MATRIX

fixed in repeated samples, then the only source of variation is in the e vector and hence in Y .

additionally we may assume that conditional on X (fixed)

$$7. \quad e_{kt} \sim N(0, \sigma^2 I_T) \quad \text{and hence}$$

$$y_{kt} \sim N(x_{kt} \beta_1, \sigma^2 I_T)$$

ESTIMATION BY OLS

OLS estimate for β minimizes $\sum e_t^2$, i.e:

$$\begin{aligned} S(\beta_1, \beta_2, \dots, \beta_K) &= \sum_{t=1}^T [y_t - E_x(y_t)]^2 \\ &= \sum_{t=1}^T (y_t - \beta_1 - \beta_2 x_{t2} - \dots)^2 \end{aligned}$$

We differentiate S. w.r.t. to $\beta_1, \beta_2 \dots \beta_K$ and set the derivatives = 0.

The partial derivatives are equal to zero for $b_1, b_2 \dots b_K$ which are ESTIMATES OF $\beta_1, \beta_2 \dots \beta_K$, at the minimum of $S(\beta)$.

$$\frac{\partial S}{\partial \beta_1} = 2T\beta_1 + 2\beta_2 \sum x_{t2} + 2\beta_3 \sum x_{t3} - 2 \sum y_t$$

$$\frac{\partial S}{\partial \beta_2} = 2\beta_1 \sum x_{t2} + 2\beta_2 \sum x_{t2}^2 + 2\beta_3 \sum x_{t2} x_{t3} - 2 \sum x_{t2} y_t$$

$$\frac{\partial S}{\partial \beta_3} = 2\beta_1 \sum x_{t3} + 2\beta_2 \sum x_{t2} x_{t3} + 2\beta_3 \sum x_{t3}^2 - 2 \sum x_{t3} y$$

$$\frac{\partial S}{\partial \beta_1} = 0 \Rightarrow T b_1 + \sum x_{t2} \cdot b_2 + \sum x_{t3} b_3 = \sum y_t$$

$$\frac{\partial S}{\partial \beta_2} = 0 \Rightarrow \sum x_{t2} b_1 + \sum x_{t2}^2 \cdot b_2 + \sum x_{t2} x_{t3} b_3 = \sum x_{t2} y$$

$$\frac{\partial S}{\partial \beta_3} = 0 \Rightarrow \sum x_{t3} b_1 + \sum x_{t2} x_{t3} b_2 + \sum x_{t3}^2 b_3 = \sum x_{t3} y$$

$$\begin{bmatrix} T & \sum x_{t2} & \sum x_{t3} \\ \sum x_{t2} & \sum x_{t2}^2 & \sum x_{t2} x_{t3} \\ \sum x_{t3} & \sum x_{t2} x_{t3} & \sum x_{t3}^2 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} \sum y_t \\ \sum x_{t2} y \\ \sum x_{t3} y \end{bmatrix}$$

$$X' X \mathbf{b} = X' y$$

$$\mathbf{b} = (X' X)^{-1} X' y$$

again b has the "blue" property, in particular:

$$b = (X'X)^{-1} X' (X\beta + e)$$

$$b = (X'X)^{-1} X' X \beta + (X'X)^{-1} X' e$$

$$\mathbb{E}(b) = \beta \quad \text{since}$$

$$\mathbb{E}((X'X)^{-1} X' e) = (X'X)^{-1} X' \mathbb{E}(e) = 0$$

$$(X'X)^{-1} X' e$$

$$\mathbb{E}(X'e) = 0$$

by Assumptions 2 and 5. $\mathbb{E}(X'e) = X'E(e) = 0$

estimation of σ^2

$$\hat{\sigma}^2 = \frac{\sum \hat{e}_t^2}{T-K} = \frac{\hat{e}' \hat{e}}{T-K} = \frac{(Y - X\beta)'(Y - X\beta)}{T-K}$$

K: K degrees of freedom are lost = 1 can pin down
K among T residuals: one from the condition
 $\sum \hat{e}_t = 0$, one for $\sum x_{t1} \hat{e}_t = 0$, one for $\sum x_{t2} \hat{e}_t = 0$
etc till $\sum x_{tK} \hat{e}_t = 0$

We have shown that \hat{b} is unbiased. Its variance, as in the simple regression is:

$$\text{var}(\hat{b}) = E[(\hat{b} - \beta)(\hat{b} - \beta)'] =$$

$$\begin{bmatrix} \underline{\text{var } b_1} & \text{cov}(b_1, b_2) & \text{cov}(b_1, b_3) & \dots \\ \text{cov}(b_2, b_1) & \underline{\text{var } b_2} & \text{cov}(b_2, b_3) & \dots \\ \text{cov}(b_3, b_1) & \text{cov}(b_3, b_2) & \underline{\text{var } b_3} & \dots \\ \vdots & \vdots & \vdots & \vdots \\ & & & \underline{\text{var } b_K} \end{bmatrix}$$

$$= \sigma^2(X'X)^{-1} = \sigma^2 \begin{bmatrix} T & \sum x_{t2} & \sum x_{t3} \\ \sum x_{t2} & \sum x_{t2}^2 & \sum x_{t2}x_{t3} \\ \sum x_{t3} & \sum x_{t2}x_{t3} & \sum x_{t3}^2 \end{bmatrix}$$

$$\widehat{\text{var}}(\hat{b}) = \widehat{\sigma}^2(X'X)^{-1} = \widehat{\sigma}^2 \begin{bmatrix} & X'X & \\ & \vdots & \vdots \\ & X'X & \end{bmatrix}$$

R² : COEFFICIENT OF DETERMINATION

measures the proportion of variation in the dependent var. that is explained by variation in the explanatory variable (regressors)

$$R^2 = \frac{\text{variation in } y \text{ accommodated by explanatory var}}{\text{total variation in } y} = \frac{ESS}{TSS}$$

$$TSS = RSS + ESS$$

$$= \frac{\sum (y_t - \bar{y})^2}{\sum (\hat{y}_t - \bar{y})^2} = 1 - \frac{\text{error variation}}{\text{total variation}} = 1 - \frac{RSS}{TSS}$$

$$= 1 - \frac{\sum \hat{e}_t^2}{\sum (y_t - \bar{y})^2} = 1 - \frac{\hat{e}' \hat{e}}{y'y - T\bar{y}^2}$$

Sometimes it is useful to compute the adjusted R²:

$$\bar{R}^2 = 1 - \frac{\hat{e}' \hat{e} / (T-K) - \bar{r}^2}{y'y - T\bar{y}^2 / (T-1)} = 1 - \frac{RSS / (T-K)}{TSS / (T-1)}$$

Since $R^2 = 1 - \frac{\hat{e}' \hat{e} / T}{y'y - T\bar{y}^2 / T}$, we have

$$\hat{R}^2 = 1 - \frac{T-1}{T-K} (1-R^2) = \frac{1-K}{T-K} + \frac{T-1}{T-K} R^2$$

When we add a regressor $\sum \hat{\epsilon}_t^2 \downarrow$ But does the addition of an extra regressor improve the explanatory power of regressors?

Well, R^2 always \uparrow when we add a regressor, hence we can be mislead and believe that an extra regressor improves the fit.

If an additional var. produces too small a reduction in $(1-R^2)$ to compensate for the increase in $\frac{(T-1)}{(T-K)}$, \hat{R}^2 will decline.

Note: for $R^2=0$, $\hat{R}^2 = 1 - \frac{T-1}{T-K}$ and can be negative.

Note also that if in a regression we omit the constant, without a constant

$$\sum (y_t - \bar{y})^2 \neq \sum (\hat{y}_t - \bar{y})^2 + \sum \hat{\epsilon}_t^2$$

$$\text{TSS} \neq \text{ESS} + \text{RSS}$$

UNLESS: WE REGRESS $\tilde{y} = y - \bar{y}$ on $\tilde{x} = x - \bar{x}$!