

THE AUTOREGRESSIVE PROCESSES

- AR means that Z_t depends on its past values, i.e. on Z_{t-1} , Z_{t-2} , etc. Depending on the number of those past Z values, which determine the present Z_t , we distinguish

AR(1) : Z_t depends on Z_{t-1} only

AR(2) : Z_t Z_{t-1} and Z_{t-2}

AR(3) : Z_t Z_{t-1} , Z_{t-2} and Z_{t-3}

or, in general : on p past values of Z_t :

AR(p)

- the simplest model is the AR(1)

AR(1) IS DEFINED AS:

$$Z_t = \mu + \phi_1 Z_{t-1} + a_t$$

- a_t IS A WHITE NOISE (SEQUENCE OF UNCORRELATED R.V.); $a_t \sim (0, \sigma_a^2) \Rightarrow E(a_t) = 0$ and $\text{var}(a_t) = \sigma_a^2$
with $\text{cov}(a_t, a_{t+k}) = 0 \quad \forall k \neq 0$.

$$E(a_t Z_{t-1}) = 0 \Rightarrow \text{cov}(a_t, Z_{t-1}) = 0$$

- ϕ_1 IS THE AUTO REGRESSIVE COEFFICIENT. ITS VALUE IS CRUCIAL AS IT DETERMINES IF THE PROCESS IS STATIONARY
- δ IS A CONSTANT

AR(1) IS STATIONARY $\Leftrightarrow |\phi_1| < 1$

$\Rightarrow$ to check, we consider the mean, variance and covariance

$$E(Z_t) = E[\delta + \phi_1 Z_{t-1} + a_t]$$

$$\text{suppose } E(Z_t) = E(Z_{t-1}) = \dots = \mu$$

$$E(Z_t) = \frac{\delta}{1 - \phi_1} = \mu$$

FROM NOW ON, FOR CONVENIENCE WE ASSUME THAT THE ORIGINAL TIME SERIES HAS BEEN TRANSFORMED BY REMOVING THE MEAN μ FROM ALL REALIZATIONS $t=1, \dots, n$

$$\dot{Z}_t = Z_t - \frac{\delta}{1 - \phi_1} = Z_t - \mu$$

$$\text{and } E(\dot{Z}_t) = 0$$

3.

$$\text{var}(\dot{z}_t) = \text{var}(\phi_1 \dot{z}_{t-1} + a_t)$$

$$= \phi_1^2 \text{var}(\dot{z}_{t-1}) + \text{var}(a_t)$$

because $\dot{z}_{t-1}$ and a_t are
UNCORRELATED

$$= \phi_1^2 \text{var}(\dot{z}_t) + \sigma_a^2$$

by stationarity $\text{var}(\dot{z}_{t-1}) = \text{var}(\dot{z}_t)$

$$\text{var}(\dot{z}_t) = \frac{\sigma_a^2}{1 - \phi_1^2}$$

autocovariances

$$\gamma_0 = \text{var}(\dot{z}_t) = \frac{\sigma_a^2}{1 - \phi_1^2}$$

at lag 1:

$$\text{cov}(\dot{z}_t, \dot{z}_{t-1}) = E \left[(\dot{z}_t - E(\dot{z}_t)) (\dot{z}_{t-1} - E(\dot{z}_{t-1})) \right]$$

$$= E \left[\dot{z}_t \dot{z}_{t-1} \right]$$

$$= E \left[(\phi_1 \dot{z}_{t-1} + a_t) \dot{z}_{t-1} \right] =$$

$$= \phi_1 E(\dot{z}_{t-1}^2) + E(a_t \dot{z}_{t-1})$$

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$$\gamma_1 = \phi_1 \gamma_0$$

0 because
 a_t and $\dot{z}_{t-1}$ uncorrelated

the same result holds for

$\text{cov}(\dot{z}_{t-1}, \dot{z}_{t-2}), \text{cov}(\dot{z}_{t-5}, \dot{z}_{t-6})$, i.e. all $\dot{z}$ values
one period apart

at lag 2:

$$\begin{aligned}\text{cov}(\dot{z}_t, \dot{z}_{t-2}) &= E[(\dot{z}_t - E(\dot{z}_t))(\dot{z}_{t-2} - E(\dot{z}_{t-2}))] \\ &= E[\dot{z}_t \dot{z}_{t-2}] \\ &= E[(\phi_1 \dot{z}_{t-1} + a_t) \dot{z}_{t-2}] \\ &= \phi_1 E(\dot{z}_{t-1} \dot{z}_{t-2}) + \underbrace{E[a_t \dot{z}_{t-2}]}_0\end{aligned}$$

$$\gamma_2 = \phi_1 \cdot \phi_1 \gamma_0 = \phi_1^2 \gamma_0$$

We can generalize these results for any lag $k=1, 2, \dots$

$$\gamma_k = \phi_1^k \gamma_0 = \text{cov}(\dot{z}_t, \dot{z}_{t-k})$$

THIS IS THE AUTOCOVARIANCE FUNCTION OF AR(1)

THE AUTOCORRELATION FUNCTION (ACF) OF AR(1)

$$\rho_k = \frac{\gamma_k}{\gamma_0} = \phi_1^k$$

ACF

lag	K	ρ_K	if $\phi_1 = 0.3$	if $\phi_1 = 0.9$
0		1		
1		ϕ_1		
2		ϕ_1^2		
3		ϕ_1^3		
4		ϕ_1^4		

Note that given $|\phi_1| < 1$, the ACF gradually die out to zero. The rate is expo and the pace depends on the value of ϕ_1 .

The effect of the initial condition $\dot{Z}_0$ on $\dot{Z}_t$:

$$\begin{aligned}
 \dot{Z}_t &= \phi_1 \dot{Z}_{t-1} + a_t \\
 &= \phi_1 (\phi_1 \dot{Z}_{t-2} + a_{t-1}) + a_t \\
 &= \phi_1^2 (\phi_1 \dot{Z}_{t-3} + a_{t-2}) + a_t + \phi_1 a_{t-1} \\
 &= \phi_1^3 (\phi_1 \dot{Z}_{t-4} + a_{t-3}) + a_t + \phi_1 a_{t-1} + \phi_1^2 a_{t-2} \\
 &\vdots \\
 &= \phi_1^t \dot{Z}_0 + a_t + \phi_1 a_{t-1} + \phi_1^2 a_{t-2} + \dots + \phi_1^{t-1} a_1
 \end{aligned}$$

estimation of ACF:

$$\hat{\rho}_1 = \frac{\hat{cov}(\dot{z}_t, \dot{z}_{t-1})}{\hat{var} \dot{z}_t} = \frac{\sum_{t=2}^n \dot{z}_t \cdot \dot{z}_{t-1}}{\sum_{t=1}^n \dot{z}_t^2}$$

$$\hat{\rho}_2 = \frac{\hat{cov}(\dot{z}_t, \dot{z}_{t-2})}{\hat{var} \dot{z}_t} = \frac{\sum_{t=3}^n \dot{z}_t \cdot \dot{z}_{t-2}}{\sum_{t=1}^n \dot{z}_t^2}$$

testing for white noise:

$$H_0: \rho_1 = 0$$

$$\text{under } H_0: \sqrt{n} \hat{\rho}_1 \stackrel{a}{\sim} N(0, 1)$$

$$\text{Reject } H_0 \text{ if } |\hat{\rho}_1| \geq \frac{1.96}{\sqrt{n}} \text{ or } \frac{2}{\sqrt{n}}$$

AR(2):

$$Z_t = \delta + \phi_1 Z_{t-1} + \phi_2 Z_{t-2} + a_t$$

$$E(Z_t) = E(Z_{t-1}) = E(Z_{t-2}) = \mu$$

$$\mu = \delta + \phi_1 \mu + \phi_2 \mu$$

$$E(Z_t) = \frac{\delta}{1 - \phi_1 - \phi_2} = \mu$$

FOR STATIONARITY OF AR(2) WE REQUIRE:

$$1. \quad \phi_2 + \phi_1 < 1$$

$$2. \quad \phi_2 - \phi_1 < 1$$

$$3. \quad |\phi_2| < 1$$

Let $\dot{Z}_t = Z_t - \mu$, and recall $B \dot{Z}_t = \dot{Z}_{t-1}$, $B^2 \dot{Z}_t = \dot{Z}_{t-2}$

$$\dot{Z}_t = \phi_1 B \dot{Z}_t + \phi_2 B^2 \dot{Z}_t + a_t$$

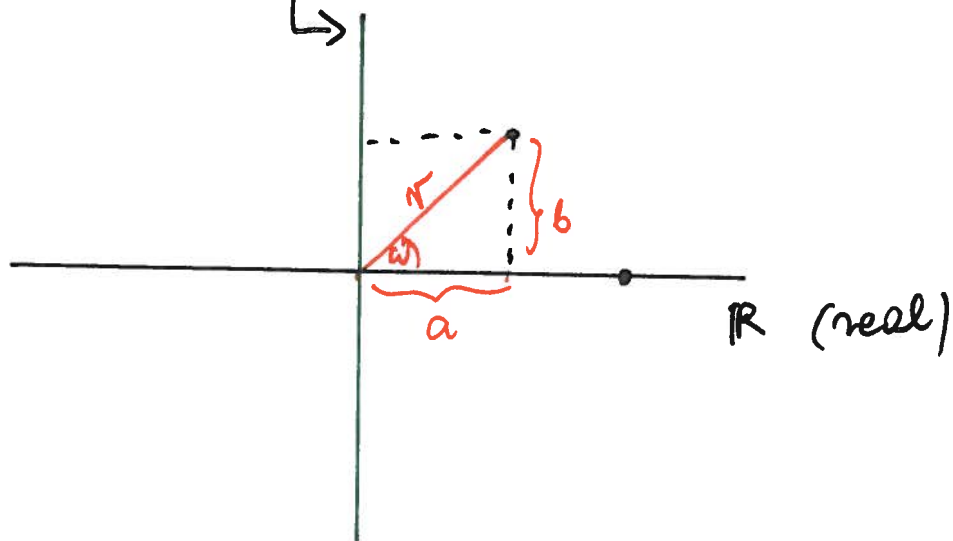
$$\dot{Z}_t (1 - \phi_1 B - \phi_2 B^2) = a_t$$

The polynomial in B has roots outside the unit circle, i.e. of modulus greater than 1 if 1., 2., 3. hold.

$$i = \sqrt{-1}$$

Imaginary

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the modulus of a real number = absolute value

modulus of an imaginary # $a \pm bi \Rightarrow r = \sqrt{a^2 + b^2}$

AR(2) has an autoregressive polynomial of order 2 in B :

$$1 - \phi_1 B - \phi_2 B^2 = 0$$

$$\text{or } -\phi_2 B^2 - \phi_1 B + 1 = 0$$

Which has two (or one) roots B_1, B_2 either real or imaginary

$$B_i = \frac{\phi_1 \pm \sqrt{\Delta}}{-2\phi_2}, \quad i=1,2, \quad \text{depending on } \Delta = \phi_1^2 + 4\phi_2$$

being greater, equal or less than zero.

conditions 1, 2 $\Rightarrow$ if roots B_1, B_2 real, then **greater > 1**
in absolute value

condition 3 $\Rightarrow$ if roots imaginary $a+bi = r \cos \omega + ri \sin \omega$
then the oscillations are damped if
greater > 1 IN MODULUS

autocovariances.

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$$\gamma_0 = E(\dot{Z}_t^2) \text{ is the var}(\dot{Z}_t)$$

$$\begin{aligned} \bullet \gamma_0 &= E[(\phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-2} + a_t) \dot{Z}_t] \\ &= \phi_1 \gamma_1 + \phi_2 \gamma_2 + \sigma_a^2 \end{aligned}$$

$$\begin{aligned} \bullet \gamma_k &= E[\dot{Z}_{t-k} \dot{Z}_t] = E[\dot{Z}_{t-k} (\phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-2} + a_t)] \\ &= \phi_1 \gamma_{k-1} + \phi_2 \gamma_{k-2} \end{aligned}$$

ACF of AR(2):

$$\bullet \rho_k = \phi_1 \rho_{k-1} + \phi_2 \rho_{k-2} \quad \text{for } k > 2$$

$$\text{and } \rho_1 = \frac{\phi_1}{1 - \phi_2}, \quad \rho_2 = \phi_2 + \frac{\phi_1^2}{1 - \phi_2}$$

AR(p) : STATIONARITY: The roots of the autoregressive polynomial have to lie outside the unit circle.

AR(p) have no autocorrelations and ACF defined by
Yule-Walker equations

$$\gamma_k = \phi_1 \gamma_{k-1} + \dots + \phi_p \gamma_{k-p} \quad k > 0$$

$$\rho_k = \phi_1 \rho_{k-1} + \dots + \phi_p \rho_{k-p} \quad k > 0$$