

IDENTIFICATION AR(p)

To find the order p of an AR(p) we use the PACF: partial autocorrelation function.

- the values of the PACF equal the last coefficient in a regression of Z_t on its lagged values:

$$Z_t = \delta + \phi_{11} Z_{t-1} + a_t \Rightarrow \hat{\phi}_{11}$$

$$Z_t = \delta + \phi_{21} Z_{t-1} + \phi_{22} Z_{t-2} + a_t \Rightarrow \hat{\phi}_{22}$$

$$Z_t = \delta + \phi_{31} Z_{t-1} + \phi_{32} Z_{t-2} + \phi_{33} Z_{t-3} + a_t \Rightarrow \hat{\phi}_{33}$$

\vdots

- the argument of PACF is the lag:

lag	PACF
(Z_{t-1})	ϕ_{11}
(Z_{t-2})	ϕ_{22}
(Z_{t-3})	ϕ_{33}
(Z_{t-4})	ϕ_{44}

Intuition: ϕ_{22} measures the linear dependence between z_t and z_{t-2} WHILE REMOVING THE EFFECT OF z_{t-1}

PACF IS USED TO FIND THE ORDER p of AR(p)
 PACF cuts off after p lags: the last value of PACF that is significantly different from 0 indicates the order p

Test of ϕ_{kk} :

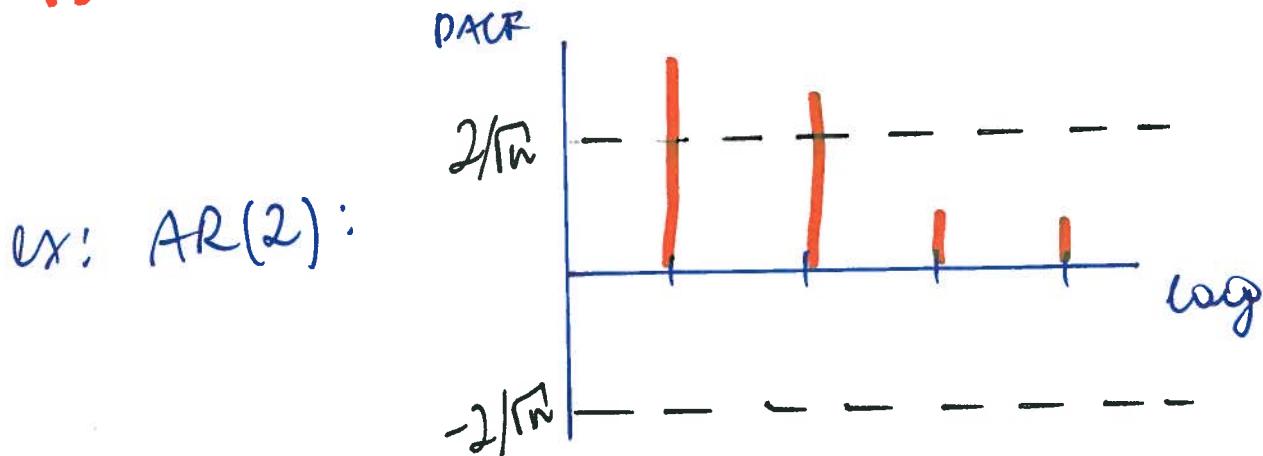
UNDER H_0 : no linear dependence between z_t and z_{t-p}

z_{t-p} :

$$\hat{\phi}_{pp} \sim N(0, \frac{1}{n})$$

$$\Rightarrow \hat{\theta}_{pp} \pm 1.96 \cdot \frac{1}{\sqrt{n}}$$

IS THE CONFIDENCE INTERVAL



ESTIMATION OF AR(ϕ)

ASSUME THAT ORDER p IS KNOWN

$$Z_t = \delta + \phi_1 Z_{t-1} + \phi_2 Z_{t-2} + \dots + \phi_p Z_{t-p} + \epsilon_t$$

OLS

- the regressors are stochastic
 - the arrays $\{Z_t, Z_{t-1}, Z_{t-2}, \dots, Z_{t-p}\}$ are not independent & t , but serially correlated instead
 - error ϵ_t is correlated with future values of regressors
- OLS is biased in the presence of lagged endogenous variable among the regressors, but it is nevertheless CONSISTENT, i.e. valid in large sample.

$$y_{p+1} = \delta + \phi_1 y_p + \phi_2 y_{p-1} + \phi_3 y_{p-2} + \dots + \phi_p y_1 + \epsilon_{p+1}$$

$$y_{p+2} = \delta + \phi_1 y_{p+1} + \phi_2 y_p + \phi_3 y_{p-1} + \dots + \phi_p y_2 + \epsilon_{p+2}$$

⋮

$$y_n = \delta + \phi_1 y_{n-1} + \phi_2 y_{n-2} + \phi_3 y_{n-3} + \dots + \phi_p y_{n-p} + \epsilon_n$$

$$\begin{bmatrix} y_{p+1} \\ y_p \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & y_p & y_{p-1} & \cdots & \cdots & \cdots & y_1 \\ 1 & y_{p-1} & y_p & \ddots & & & y_2 \\ \vdots & \vdots & \vdots & \ddots & & & \vdots \\ \vdots & \vdots & \vdots & \ddots & & & \vdots \\ 1 & y_{n-1} & y_{n-2} & \cdots & \cdots & \cdots & y_{n-p} \end{bmatrix} \begin{bmatrix} \delta \\ \phi_1 \\ \phi_2 \\ \vdots \\ \phi_p \end{bmatrix} + \begin{bmatrix} \epsilon_{p+1} \\ \epsilon_{p+2} \\ \vdots \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$Y = X\beta + \epsilon$$

$$\hat{\beta} = (X'X)^{-1}X'y$$

$$\text{var}(\hat{\beta}) = \hat{\sigma}^2 (X'X)^{-1}$$

$$\hat{\sigma}^2 = \frac{\hat{\epsilon}' \hat{\epsilon}}{n-2p-1} = \frac{(Y - X\hat{\beta})' (Y - X\hat{\beta})}{n-2p-1}$$

because $T-p$ can be used for estimation of AR(p)
 $p+1$ coefficients to estimate (ϕ 's + intercept)

$$\hat{u} = \frac{f}{1 - \hat{\phi}_1 - \dots - \hat{\phi}_p}$$

MLE

Consider:

$$a_{p+1} = z_{p+1} - \delta - \phi_1 z_p - \phi_2 z_{p-1} - \dots - \phi_p z_1$$

$$a_{p+2} = z_{p+2} - \delta - \phi_1 z_{p+1} - \phi_2 z_p - \dots - \phi_p z_2$$

⋮

$$a_n = z_n - \delta - \phi_1 z_{n-1} - \phi_2 z_{n-2} - \dots - \phi_p z_{n-p}$$

ASSUME THAT a_1, a_2, \dots, a_n are IID $N(0, \sigma^2)$
 i.e. are STRONG White Noise and are normally distributed

$$f(a_1, a_2, \dots, a_n) = f(a_1) \cdot f(a_2) \cdots \cdots f(a_n)$$

$$\ln L(\delta, \phi_1, \phi_2, \dots, \phi_p | z_1, z_2, \dots, z_n) =$$

$$-\frac{n}{2} \ln(2\pi) - \frac{n}{2} \ln \sigma^2 - \frac{1}{2} \sum_{t=p+1}^n \frac{(z_t - \delta - \phi_1 z_{t-1} - \dots - \phi_p z_{t-p})^2}{\sigma^2}$$

- backtesting to recover ϕ_1, \dots, ϕ_p can be used.
- estimators are **CONSISTENT**
 - asymptotically efficient
 - asymptotically normally distributed.

$$\sqrt{n} (\hat{\phi}_n - \phi_0) \stackrel{a}{\sim} N(0, I^{-1})$$

where $\hat{\phi}_n = \begin{bmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \\ \vdots \\ \hat{\phi}_p \\ \delta \end{bmatrix}$, $\phi_0 = \begin{bmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_p \\ \delta \end{bmatrix}$ and $I = E \left[-\frac{\partial^2 \ln L}{\partial \phi \partial \phi^T} \right]$

is the information matrix

test are asymptotically valid.

Wald $\frac{\hat{m}(\hat{\phi}_K - \phi_{0K})}{\sqrt{\text{var } \hat{\phi}_K}} \stackrel{a}{\sim} N(0,1)$

To test $H_0: \phi_K = 0$ use the "t-ratio"

$$\text{"t"} = \frac{\hat{\phi}_K}{\sqrt{\text{var } \hat{\phi}_K}}$$

under H_0 "t" is asymptotically $N(0,1)$ distributed

In practice, the Information matrix inverse is approximated by the inverse of the Hessian matrix or the outer product of scores:

$$\hat{I}_n = -\frac{1}{n} \sum_{t=1}^n \frac{\partial^2 \ln L}{\partial \phi \partial \phi'} \approx \frac{1}{n} \sum_{t=1}^n \frac{\partial \ln L}{\partial \phi} \frac{\partial \ln L'}{\partial \phi}$$

The variances of each estimated ϕ_K are on the main diagonal of \hat{I}_n^{-1}

Note that ~~This~~ MLE and OLS are asymptotically equivalent,

$$\text{because } \min \sum_{t=p+1}^n e_t^2 = \sum_{t=p+1}^n (z_t - \delta - \phi_1 z_{t-1} - \dots - \phi_p z_{t-p})$$

is equivalent to maximizing $\ln L$ with respect to ϕ_1, \dots, ϕ_p and δ .
Next, the estimator of σ^2 can be obtained.

Other useful tests:

Likelihood ratio:

$$2[\ln L(\hat{\phi}_n) - \ln L(\hat{\phi}_n^c)] \stackrel{a}{\sim} \chi^2(r)$$

Note also that at the maximum, we have

$$\begin{aligned} \ln L &= -\frac{n}{2} \ln(2\pi) - \frac{n}{2} \ln \hat{\sigma}_a^2 - \frac{1}{2} \frac{n \hat{\sigma}_a^2}{\hat{\sigma}_a^2} \\ &\simeq -\frac{n}{2} \ln \hat{\sigma}_a^2 - \frac{n}{2} \end{aligned}$$

MA(q)

Moving average of order q

$$Z_t = \mu + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2} - \cdots - \theta_q a_{t-q}$$

- mean

$$E(Z_t) = \mu$$

- variance

$$\begin{aligned}\sigma_0^2 &= \text{var}(Z_t) = E(Z_t - \mu)^2 \\ &= E(a_t^2 + \theta_1^2 a_{t-1}^2 + \cdots + \theta_q^2 a_{t-q}^2 \\ &\quad - 2\theta_1 \theta_2 a_{t-1} a_{t-2} - \cdots) \\ &= \sigma_a^2 + \theta_1^2 \sigma_a^2 + \cdots + \theta_q^2 \sigma_a^2 \\ &= \sigma_a^2 (1 + \theta_1^2 + \cdots + \theta_q^2)\end{aligned}$$

Ex: MA(1)

$$Z_t = \mu + a_t - \theta_1 a_{t-1}$$

- $E(Z_t) = \mu$

- $\sigma_0^2 = \text{var}(Z_t) = E(Z_t - \mu)^2 = \sigma_a^2 (1 + \theta_1^2)$

$$\begin{aligned}\gamma_1 &= \text{cov}(z_t, z_{t-1}) = E[(z_t - \mu)(z_{t-1} - \mu)] \\ &= E[(a_t - \theta_1 a_{t-1})(a_{t-1} - \theta_1 a_{t-2})] \\ &= \theta_1^2 \sigma_a^2\end{aligned}$$

$$\begin{aligned}\gamma_2 &= \text{cov}(z_t, z_{t-2}) = E[(z_t - \mu)(z_{t-2} - \mu)] \\ &= E[(a_t - \theta_1 a_{t-1})(a_{t-2} - \theta_1 a_{t-3})] \\ &= 0\end{aligned}$$

THE ACF OF A MA(q) CUTS OFF AT LAG q INDICATING THE ORDER OF MA(q)

⇒ USE ACF TO FIND THE ORDER OF MA (IDENTIFICATION)

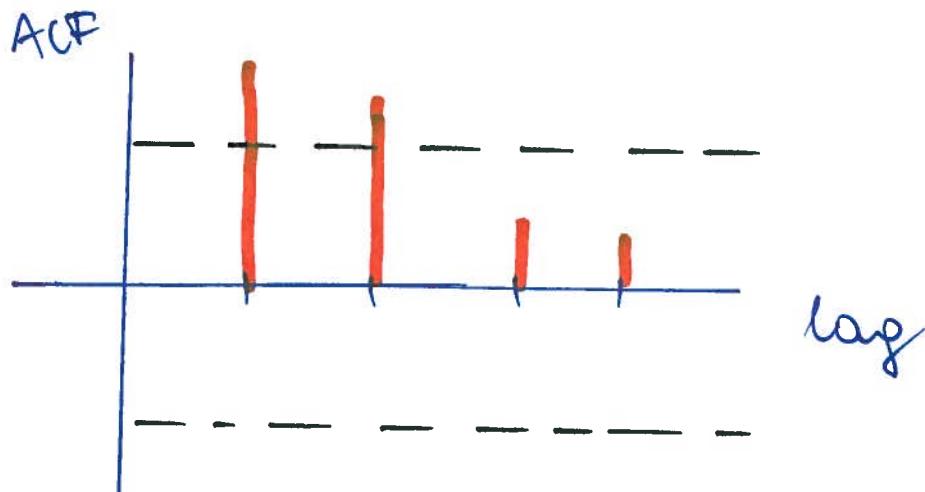
$$\rho_K = \frac{\gamma_K}{\gamma_0} = \begin{cases} \frac{\theta_1}{1+\theta_1^2}, & K=1 \\ 0, & K>1 \end{cases}$$

Recall, under $H_0 : \rho_K = 0$ we have

$$\hat{\rho}_K \stackrel{d}{\sim} N(0, \frac{1}{n})$$

and $\hat{\rho}_K \pm 1.96 \cdot \frac{1}{\sqrt{n}}$ is the confidence interval.

MA(2):



MA(2):

$$Z_t = \mu + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}$$

- $E(Z_t) = \mu$
- $\sigma_0^2 = \text{var}(Z_t) = \sigma_a^2 (1 + \theta_1^2 + \theta_2^2)$
- $\sigma_1 = \text{cov}(Z_t, Z_{t-1}) = E[(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2})(a_{t-1} - \theta_1 a_{t-2} - \theta_2 a_{t-3})]$
 $= \theta_1 \sigma_a^2 + \theta_1 \theta_2 \sigma_a^2 = \sigma_a^2 (\theta_1 + \theta_1 \theta_2)$
- $\sigma_2 = \text{cov}(Z_t, Z_{t-2}) = E[(a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2})(a_{t-2} - \theta_1 a_{t-3} - \theta_2 a_{t-4})] = \theta_2 \sigma_a^2$

$$\gamma_3 = \text{cov}(\hat{\epsilon}_t, \hat{\epsilon}_{t-3}) = E[(\alpha_t - \theta_1 \alpha_{t-1} - \theta_2 \alpha_{t-2})(\alpha_{t-3} - \theta_1 \alpha_{t-4} - \theta_2 \alpha_{t-5})] = 0$$

for MA(2) :

$$\rho_1 = \frac{\theta_1(1+\theta_2)}{1+\theta_1^2+\theta_2^2}$$

$$\rho_2 = \frac{-\theta_2}{1+\theta_1^2+\theta_2^2}$$

$$\rho_k = 0 \quad \text{for } k > 2$$

ANY MA(q) IS ALWAYS STATIONARY

FOR ANY MA(q):

$$\rho_k = \begin{cases} \frac{\sum_{i=0}^{q-k} \theta_i \theta_{i+k}}{\sum_{i=0}^q \theta_i^2}, & |k| \leq q \\ 0 & |k| > q \end{cases}$$